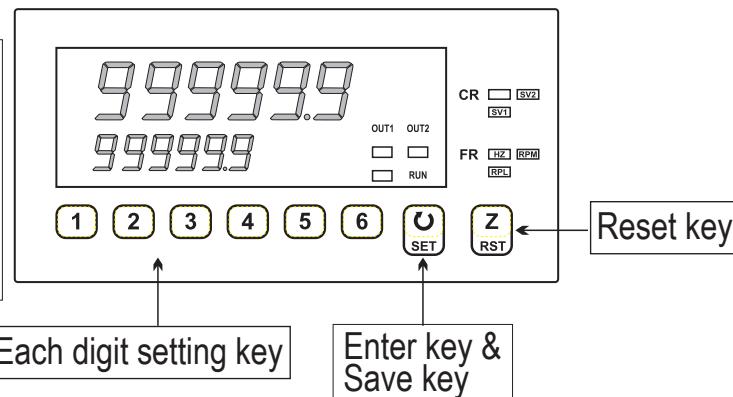


Key Function

PV(Upper LED): Actual measured value/ mode display
 SV(Lower LED): Set value/mode content display
 OUT1 : Output 1 indicator
 OUT2 : Output 2 indicator
 Hz : Frequency function indicator
 RPM : Speed function indicator
 RPL : Line speed function indicator
 RUN : Instrument operation indicator
 SET : Confirm key
 RST : Reset key
 1-6 : Number setting key, parameter modification key

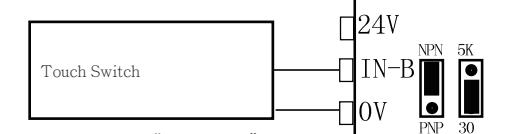
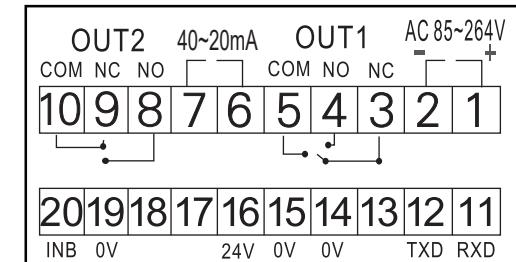
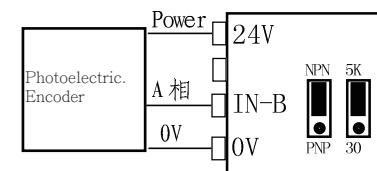
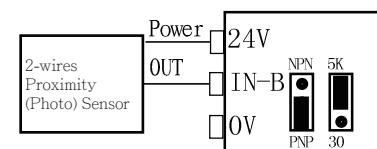
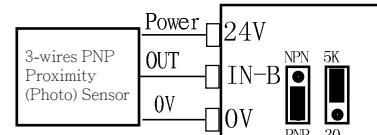
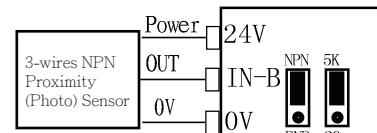


Name	Symbol	Description
Enter key & Save key		1. In the measuring status, press this key can enter to alarm setting group. 2. In the parameter setting, press this key can save the value & go to next parameter
Reset key		In any case, press the RST key, return to zero, and return to relay.
Each digit setting key		1. When setting the alarm value, press each number key to set the alarm value. 2. On the parameter setting page, press any digit key to enter the modified value set the program, and the display data will be 3 incrementally displayed.

- The following operation flow screens are (setting page code) and can be modified (the setting value will match (setting page code) flashing alternately).
- Modify (set value) all by pressing any number key. After modification, be sure to press the enter parameter setting key(.
- If you have to change the customs clearance password, you must remember it, otherwise you cannot enter it again later (parameter setting).

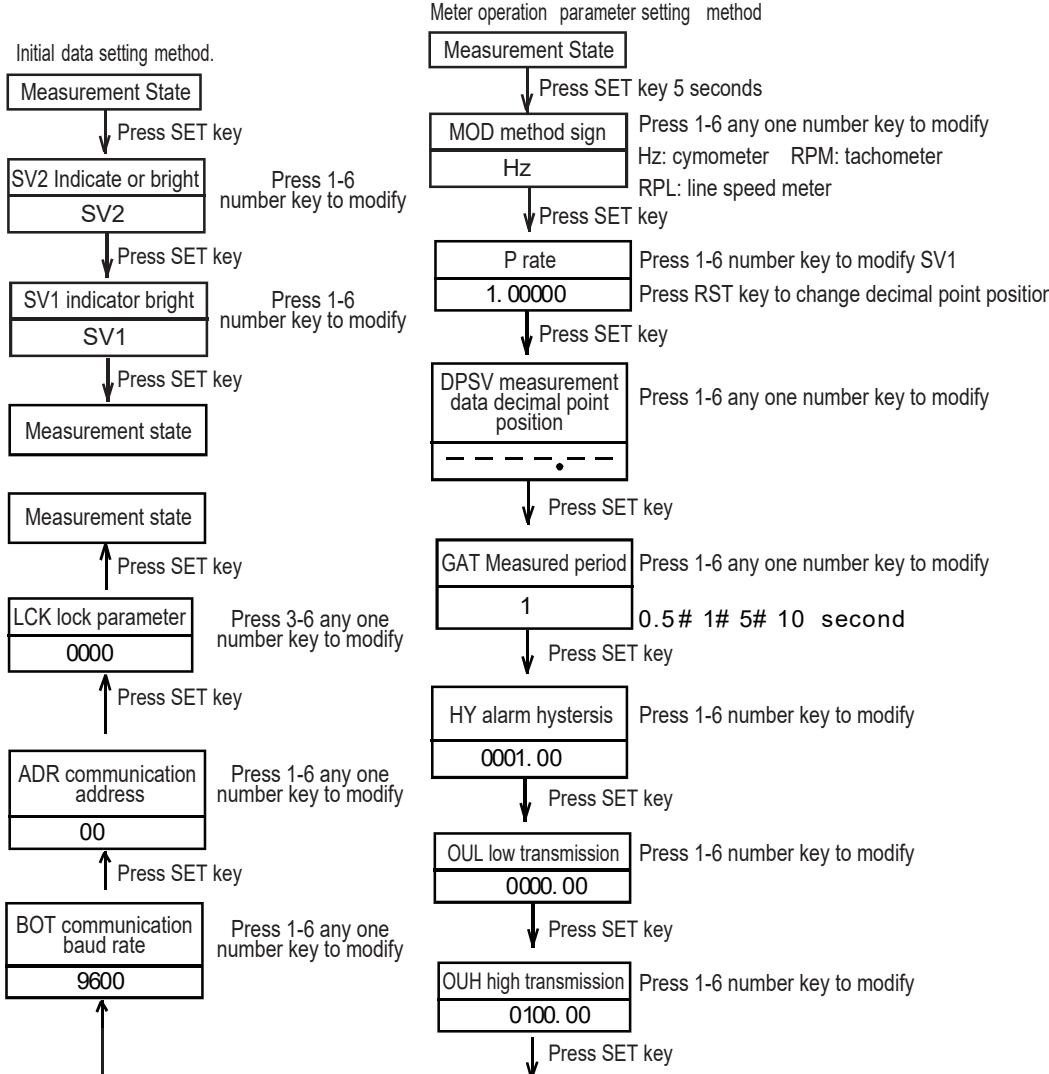
****When using the two alarm model, SV2 must > SV1.**

Wiring Connection



ATTENTION: "SWA、SW1"
Switch in the meter

Programming Mode Operating Procedures



Code	name	Instruction	initial date
Mod	Measured method	Hz Cymometer RPM Tachometer RPL Line speed meter	Hz
MOD			
P	Rate	The P can be setted When the MOD is "RPL". example1 : Encoder resolution=1000C/T , IF perimeter L=2πR=1CM , then P=L/1000=1/1000=0.001CM example2 : the wheel is being 10 hole , IF perimeter L=2πR=1CM , then P=L/10=1/10=0.1CM	1.00000
DPSV	Measurement data decimal point position	DPSV===== : 0~5000Hz (0 decimal point) 0~999999 RPM DPSV====-. : 0.0~5000.0Hz (1decimal point) 0.0~99999.9 RPM DPSV=---. : 0.00~99.99Hz (2decimal point) 0.00~999.99 RPM DPSV=---. : 0.000~99.999Hz (3decimal point) 0.000~99.999 RPM	----.-
GAT	Measured period	GAT=0.5 : 500mS(Measured one times);GAT=1 : 1second(Measured one times); GAT=5 : 5second(Measured one times); GAT=10 : 10second(Measured one times);	1
HY	HY	The parameter can not be modified when the meter uses with display only.	000.0
OUL	Low transmission	The parameter can be modified when the meter provides with transmission.	0000.0
OUH	High transmission	The parameter can be modified when the meter provides with transmission.	1000.0
ADR	Communication address	The parameter can be modified when the meter provides with communication.	00
BOT	Communication baud rate	The parameter can be modified when the meter provides with communication.	9600
LCK	LCK parameter	LCK=0000 , all the parameter can be modified ; LCK=0001 , all the parameter can not be modified but "LCK SV1 SV2" ; LCK=else , all the parameter can not be modified but "LCK" ;	0000
GAT(Measured period)		Measured range	
0.5second		2~5000Hz(cymometer) 120~999999RPM(tachometer)	
1second		1~5000Hz(cymometer) 60~999999RPM(tachometer)	
5second		0.2~5000Hz(cymometer) 12~999999RPM(tachometer)	
10second		0.1~5000Hz(cymometer) 6~999999RPM(tachometer)	

Attached picture : output method logic relationship

