



INPT	Input type selection
K2	↓ MODE
* INLO	Analog input low limit calibration
0	↓ MODE
* INHI	Analog input high limit calibration
5000	↓ MODE
* DP	Decimal point position
000.0	↓ MODE
PVLO	Lower set-point limit
0.0	↓ MODE
PVHI	Upper set-point limit
400.0	↓ MODE
* 2NLO	Remove input low limit calibration
0	↓ MODE
* 2NHI	Remove input high limit calibration
5000	↓ MODE
A1D1	Alarm mode of AL1
11	↓ MODE
A1T1	Alarm time of AL1
99.59	↓ MODE
* A2D2	Alarm mode of AL2
0	↓ MODE
* A2T2	Alarm time of AL2
99.59	↓ MODE
* A3D3	Alarm mode of AL3
0	↓ MODE
* A3T3	Alarm time of AL3
99.59	↓ MODE
HYS	Hysteresis of all alarm
0.0	↓ MODE
LO01	Output 1 low limit calibration
200	↓ MODE
HI01	Output 1 high limit calibration
3400	↓ MODE
* LO02	Output 2 low limit calibration
200	↓ MODE
* HI02	Output 2 high limit calibration
3400	↓ MODE
* LO03	Retransmission low limit calibration
0	↓ MODE
* HI03	Retransmission high limit calibration
5000	↓ MODE
* R-Y	Full run time of proportional motor
5	↓ MODE
* W-T	Wait for continued operation(Used for programmable controller)
0.0	↓ MODE
* STAL	When need the alarm of "b" point", can use this function
0000	↓ MODE
* ID	ID number
2	↓ MODE
* STOP	MODBUS
0-81	↓ MODE
* BAUD	Baudrate
9600	↓ MODE
SVOS	SV compensation
0.0	↓ MODE
PVOS	PV low compensation
0.0	↓ MODE
* C-F	Unit of PV & SV
C.	↓ MODE
S-F	Soft Filter
600	↓ MODE
PVHS	PV high compensation
0.0	↓ MODE
* H-C	Control mode
HEAT	↓ MODE
+ -	Digital Filter offset value
0.0	↓ MODE
FILT	Digital Filter
2000	↓ MODE
Return to INPT	